

# Mathematical Modelling of Neural Activity

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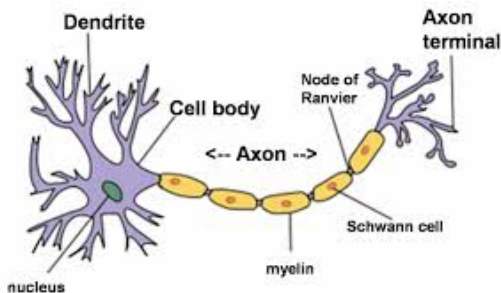
and the director of this Institution is **Prof. Evelyn Buckwar**.

# OUTLINE OF THE TALK

- 1 Introduction
- 2 Numerical Methods for the Deterministic Equation
- 3 Numerical results
- 4 Ongoing work
- 5 Stochastic Neural Field Equation
- 6 Research Project NEUROFIELD

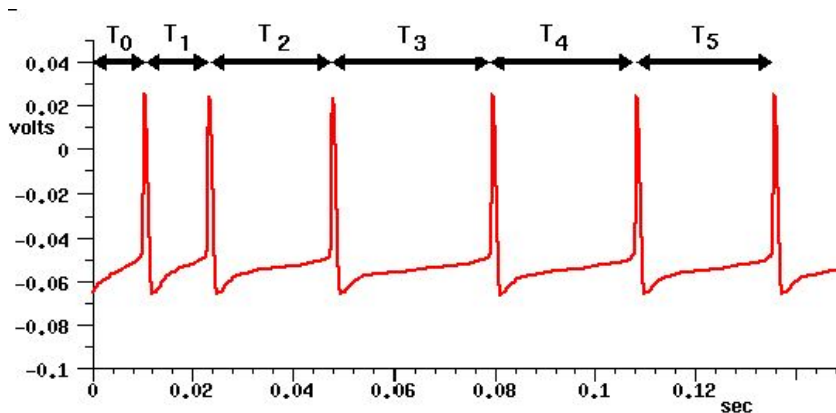
# INTRODUCTION -THE HUMAN BRAIN

According to a lower estimate from 2009, the human nervous system contains  $0.89 \times 10^{11}$  neurons, which are connected by about  $10^{15}$  synapses.



# COMMUNICATION BETWEEN NEURONS

The **change of voltage** in the cell membrane of a neuron results in a voltage spike called an **action potential**, which triggers the release of other neurotransmitters. That is, **neurons communicate with each other by firing**.

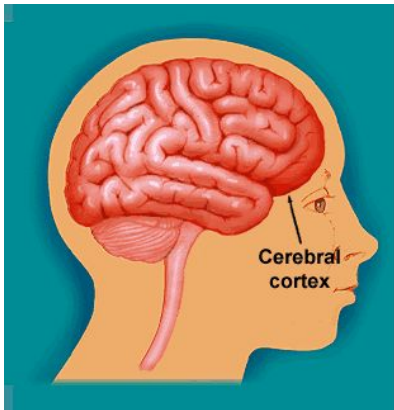


# THE CEREBRAL CORTEX

The **cerebral cortex** is the brain's outer layer of neural tissue in humans and other mammals.

It plays a key role in controlling **memory, attention, perception, awareness, thought, language** and other important processes.

The cortex of a human is about **2-4 mm thick** and contains about **one fifth** of all the neurons.



# MATHEMATICAL MODELS

- [Hodgkin and Huxley, 1952](#) - the most successful mathematical model describing the mechanism of **ion currents and voltage changes in the neuron membrane**. It consists of a system of **4 ordinary differential equations**.
- [FitzHugh-Nagumo Equations, 1962](#) - the Hodgkin-Huxley system was reduced to a system of two equations; it describes **the propagation of impulses in the nervous system**.
- [Neural Field Equations](#) - introduced by **Wilson and Cowan**, in 1972, and **Amari**, in 1977. The main idea of the **Neural Field Models** is to treat the **cortex as a continuous space** and describe the **spatiotemporal dynamics of the neural interactions**.

# APPLICATIONS OF NEURAL FIELDS

- In Neuroscience - interpretation of experimental data, including information obtained from EEG, fMRI and optical imaging.
- In Robotics - the architecture of autonomous robots, able to interact with other agents in solving a mutual task, is strongly inspired by the processing principles and the neuronal circuitry in the primate brain.



# NEURAL FIELD EQUATION

$$c \frac{\partial}{\partial t} V(\bar{x}, t) = I(\bar{x}, t) - V(\bar{x}, t) + \int_{\Omega} K(\|\bar{x} - \bar{y}\|_2) S(V(\bar{y}, t)) d\bar{y}, \quad (1)$$

$$t \in [0, T], \bar{x} \in \Omega \subset \mathbb{R}^2;$$

Initial Condition:  $V(\bar{x}, 0) = V_0(\bar{x}), \quad \bar{x} \in \Omega.$

- $V(\bar{x}, t)$  - the membrane potential in point  $\bar{x}$  at time  $t$ ;
- $I(\bar{x}, t)$  - external sources of excitation;
- $S(V)$  - dependence between the firing rate of the neurons and their membrane potentials (sigmoidal or Heaviside function);
- $K(\|\bar{x} - \bar{y}\|_2)$  - connectivity between neurons at  $\bar{x}$  and  $\bar{y}$ .

# NUMERICAL EXAMPLE 1

Connectivity Kernel:

$$K(r) = \frac{1}{\sqrt{2\pi\tilde{\zeta}_1^2}} \exp\left(-\frac{r^2}{2\pi\tilde{\zeta}_1^2}\right) - \frac{A}{\sqrt{2\pi\tilde{\zeta}_2^2}} \exp\left(-\frac{r^2}{2\pi\tilde{\zeta}_2^2}\right),$$

where  $A, \tilde{\zeta}_1, \tilde{\zeta}_2$  - given positive numbers.

External input:  $I \equiv 0$ . Firing rate function:  $S(x) = \frac{2}{1+e^{-\mu x}}$ ,  $\mu > 0$ .

Propagation speed: no delay,  $v = 1$ .

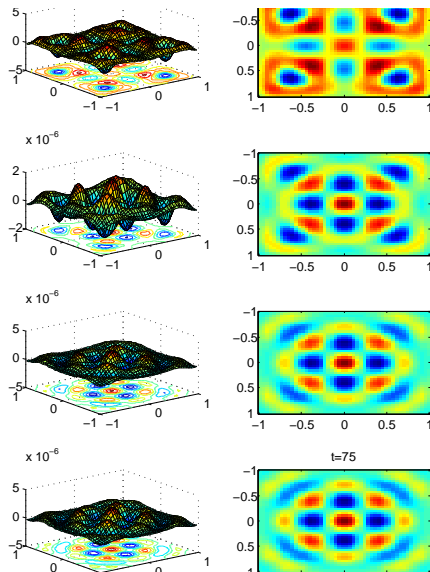
Initial condition:

$$V_0(x_1, x_2) \equiv 0.01,$$

$$\forall \bar{x} \in \Omega, t \in [-\tau_{max}, 0].$$

# NUMERICAL EXAMPLE 1

$\xi_1 = 0.1$ ,  $x_{i2} = 0.2$ ,  $A = 1$ ;  $\mu = 45$ ; no delay; time=20, 30, 40, 50.



# NUMERICAL EXAMPLE 2 (WORKING MEMORY)

Connectivity Kernel:

$$K(r) = A \exp(-kr) ((k \sin(\alpha_1 r) + \cos(\alpha_1 r)),$$

where  $r = \sqrt{x^2 + y^2}$ ,  $A = 0.02$ ,  $k = 0.8$ ,  $\alpha_1 = 1$ .

External input:

- If  $0 < t < 1.5$ ,  $I(x, t) = 0.1 \exp(-(x - 5t)^2) + 0.1 \exp(-(x - 10)^2) + 0.1 \exp(-(x + 10)^2)$ ;
- If  $1.5 \leq t < 3$ ,  $I(x, t) = 0.1 \exp(-(x - 5t)^2)$ ;
- If  $3 \leq t < 4.5$ ,  $I(x, t) = 0.1 \exp(-(x - 5t)^2) + 0.1 \exp(-(x - 10)^2) + 0.1 \exp(-(x + 10)^2)$ ;
- If  $t > 4.5$ ,  $I(x, t) = 0$ .

Firing rate function:  $S(x) = H(x - 0.1)$

Initial condition:

$$V_0(x_1, x_2) = 0$$

# NUMERICAL EXAMPLE2 (WORKING MEMORY)

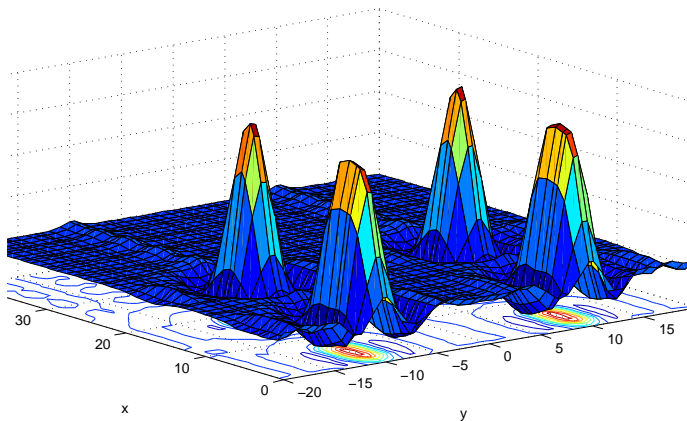


Figure: Solution at  $t = 7$  (stationary solution).

# STOCHASTIC NEURAL FIELD EQUATION

Sources of **noise** in neural fields:

- Irregularity of neuron spikes
- Non-homogeneous or irregular connectivity
- Perturbations of external stimulus

Questions we would like to answer by means of **stochastic models**:

- Does noise interfere in the **existence of stationary solutions**?
- How far the stationary solutions can be **modified** as a result of noise?
- May a stationary solution be **transformed into another** one just as a result of noise? What is the **probability** that this happens?

# STOCHASTIC MODELS

NFE with Additive Noise:

$$dU_t(x) = \left( I(x, t) - \alpha U_t(x) + \int_{\Omega} K(|x - y|) S(U_t(y)) dy \right) dt + \epsilon dW_t(x), \quad (2)$$

where  $t \in [0, T]$ ,  $x \in \Omega \subset \mathbb{R}^n$ ,  $W_t$  is a Q-Wiener process.

We consider also the following **delay** equation:

$$dU_t(x) = \left( I(x, t) - \alpha U_t(x) + \int_{\Omega} K(|x - y|) S(U_{t-\tau}(y)) dy \right) dt + \epsilon dW_t(x) \quad (3)$$

$\tau$  - delay, depending on the distance  $|x - y|$ .

**Initial condition:**

$$U_t(x) = U_0(x, t), \quad t \in [-\tau_{max}, 0], \quad x \in \Omega, \quad (4)$$

where  $U_0(x, t)$  - given stochastic process,  $\tau_{max} = |\Omega|/v$ ,  $v$  - propagation speed of the signals. We will consider domains of the form  $\Omega = [-l, l]$ , including the limit case when  $l \rightarrow \infty$ .

# ONGOING WORK

## RESEARCH PROJECT NEUROFIELD

**Main Institution:** IST-ID, University of Lisbon

**Partner:** University of Minho

**Reference:** POCI-01-0145-FEDER-031393

**Duration:** 3 years (started in September 2018)

**Budget:** 248000 E (partially supported by EU funds)

**Title :** Analysis and numerical simulation of deterministic and stochastic neural field equations with applications to robotics.

The project team includes **5 researchers** (3 - IST, 2 -Uminho).

Two of these researchers are postdocs **hired specially to work on this project.**



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